

TRANSFORMING MOBILITY: SURVEYING THE EVOLUTION AND ROBOTIC INNOVATIONS OF INTELLIGENT WHEELCHAIRS

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Abstract: This survey paper explores the transformative journey of mobility enhancement through the evolution of intelligent wheelchairs and the integration of robotic innovations. Intelligent wheelchairs have undergone remarkable advancements, evolving from conventional assistive devices to sophisticated robotic systems that enhance user autonomy and quality of life. This paper comprehensively reviews the historical progression of intelligent wheelchairs, highlighting key milestones and technological breakthroughs. It also delves into the diverse range of robotic innovations, including autonomous navigation, obstacle detection and avoidance, user intention recognition, and human-machine interface improvements, that have revolutionized intelligent wheelchairs. By examining the intersection of robotics and assistive technology, this survey offers insights into the current state of the field and its potential future directions, ultimately contributing to the broader discourse on inclusive and autonomous mobility solutions.

Keywords: Intelligent wheelchairs, robotic innovations, mobility enhancement, assistive technology, autonomous navigation, obstacle detection, user intention recognition, humanmachine interface, inclusive mobility, quality of life.

INTRODUCTION

The landscape of mobility enhancement has witnessed a remarkable transformation in recent years, with intelligent wheelchairs emerging as a pivotal area of innovation at the intersection of robotics and assistive technology. These wheelchairs, once primarily viewed as aids for individuals with limited mobility, have evolved into sophisticated robotic systems capable of providing increased autonomy and improved quality of life for users. This paper delves into the evolution and robotic innovations that have propelled intelligent wheelchairs from their conventional origins to their current state. By examining the historical development and the integration of cutting-edge technologies, this survey aims to provide a comprehensive overview of the field and its potential implications for inclusive and autonomous mobility solutions.

METHOD

To conduct this survey, a systematic and comprehensive literature review was undertaken. The review encompassed academic databases, conference proceedings, and relevant research articles spanning the evolution of intelligent wheelchairs and their robotic innovations. The search criteria were designed to identify key milestones, technological advancements, and seminal research works that have shaped the field. The collected literature was analyzed to identify common themes, trends, and patterns in the evolution of intelligent wheelchairs and the integration of robotic innovations.

The identified literature was then organized chronologically to provide a historical perspective on the development of intelligent wheelchairs. Additionally, thematic analysis was employed to categorize the various robotic innovations that have been integrated into these wheelchairs. These innovations include but are not limited to autonomous navigation algorithms, obstacle detection and avoidance systems, user intention recognition techniques, and advancements in human-machine interfaces.

By synthesizing the information gathered from the literature, this survey aims to offer a holistic view of the transformation of mobility through intelligent wheelchairs. The survey's findings and insights contribute to a deeper understanding of the field's progression and serve as a foundation for discussing the potential directions and challenges that lie ahead in the pursuit of enhancing mobility and autonomy for individuals with limited mobility.

RESULTS

The survey of the evolution and robotic innovations of intelligent wheelchairs reveals a captivating journey of progress and transformation. The historical analysis demonstrates a shift from conventional manual wheelchairs to technologically advanced intelligent wheelchairs that offer enhanced autonomy and improved user experiences. Key milestones include the development of motorized propulsion systems, the integration of basic sensors for obstacle detection, and the incorporation of computing capabilities for autonomous navigation. The examination of robotic innovations highlights the diverse range of advancements that have revolutionized intelligent wheelchairs. Autonomous navigation algorithms, utilizing techniques such as simultaneous localization and mapping (SLAM), have enabled these wheelchairs to independently navigate complex environments. Obstacle detection and avoidance systems, often employing depth sensors and machine learning algorithms, contribute to enhanced safety and user confidence. User intention recognition technologies, encompassing gesture recognition and brain-computer interfaces, empower users to control the wheelchair intuitively. Moreover, improvements in human-machine interfaces facilitate seamless interactions and greater accessibility.

DISCUSSION

The integration of robotic innovations into intelligent wheelchairs has ushered in a new era of mobility enhancement and inclusivity. These advancements not only provide practical benefits for individuals with limited mobility but also contribute to a broader societal conversation about the potential of robotics in assistive technology. Challenges persist, however, such as the need for robust and reliable navigation algorithms, ensuring user trust in autonomous systems, and addressing the financial and regulatory barriers to widespread adoption. The potential implications of these innovations are vast. As intelligent wheelchairs continue to evolve, they have the potential to redefine concepts of mobility, independence, and social integration for users. Additionally, the underlying technologies developed for intelligent wheelchairs can extend to other domains, such as service robotics and autonomous vehicles, further catalyzing technological progress.

CONCLUSION

In conclusion, the survey of the evolution and robotic innovations of intelligent wheelchairs underscores the transformative potential of merging robotics and assistive technology. From humble

beginnings as mobility aids, intelligent wheelchairs have emerged as sophisticated robotic systems that enhance user autonomy and quality of life. The integration of autonomous navigation, obstacle detection, user intention recognition, and improved human-machine interfaces has propelled these wheelchairs into a new era of mobility enhancement. While challenges remain, the journey of intelligent wheelchairs serves as a testament to human ingenuity and the power of innovation in creating inclusive and autonomous solutions for individuals with limited mobility. As the field continues to advance, it holds the promise of reshaping not only mobility but also societal perceptions of disability and autonomy.

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